

GigaDevice Semiconductor Inc.

**GD32 MCU Eclipse development
environment setup tutorial for Windows**

Application Note

AN068

Table of Contents

Table of Contents	2
List of Figures	3
List of Tables	4
1. Introduction	5
2. Development environment preparation	6
3. Tool installation instructions	7
3.1. Cross toolchains installation	7
3.1.1. ARM cross toolchains installation	7
3.1.2. RISC-V cross toolchains installation.....	7
3.2. Build Tools installation	8
3.3. Eclipse IDE installation	9
3.3.1. JDK installation	9
3.3.2. Eclipse IDE for GNU ARM & RISC-V C/C++ Developers installation.....	10
3.4. Debug Tools driver installation	11
3.4.1. OpenOCD installation	11
3.4.2. Segger J-Link installation.....	11
4. Eclipse startup and configurations	13
4.1. Create worksapce	13
4.2. Set Build Tools path	14
4.3. Set ARM Toolchains path	15
4.4. Set RISC-V Toolchains path	16
4.5. Set OpenOCD path	17
4.6. Set SEGGER J-Link path	17
5. Revision history	19

List of Figures

Figure 2-1. Download ARM cross toolchains	7
Figure 2-2. Download RISC-V cross toolchains-1	8
Figure 2-3. Download RISC-V cross toolchains-2	8
Figure 2-4. Download Build Tools-1	9
Figure 2-5. Download Build Tools-2	9
Figure 2-6. Download JDK-1	10
Figure 2-7. Download JDK-2	10
Figure 2-8. JDK version test	10
Figure 2-9. Download Eclipse-1	11
Figure 2-10. Download Eclipse-2	11
Figure 2-11. Download Eclipse-3	11
Figure 2-12. Download J-Link driver	12
Figure 3-1. Eclipse IDE Launcher	13
Figure 3-2. Eclipse workspace	14
Figure 3-3. eclipse_toolchain folder	14
Figure 3-4. Eclipse Window Preferences option	15
Figure 3-5. Set Build Tools path	15
Figure 3-6. Set ARM Toolchains path	16
Figure 3-7. Set RISC-V Toolchains path	16
Figure 3-8. Set OpenOCD path	17
Figure 3-9. Set SEGGER J-Link Path	18

List of Tables

Table 4-1. Revision history.....	19
----------------------------------	----

1. Introduction

This guide introduces how to set up the GD32 Eclipse development environment. Applicable to all GD32 MCUs.

2. Development environment preparation

- Operating system: WIN7 / WIN10 64-bit OS
- IDE: Eclipse IDE for GNU ARM & RISC-V C/C++ Developers
- Cross toolchains: arm-none-eabi-gcc / riscv-none-embed-gcc
- Build Tools: GNU MCU Eclipse build tools
- GDB server: OpenOCD / J-Link GDB Server

3. Tool installation instructions

3.1. Cross toolchains installation

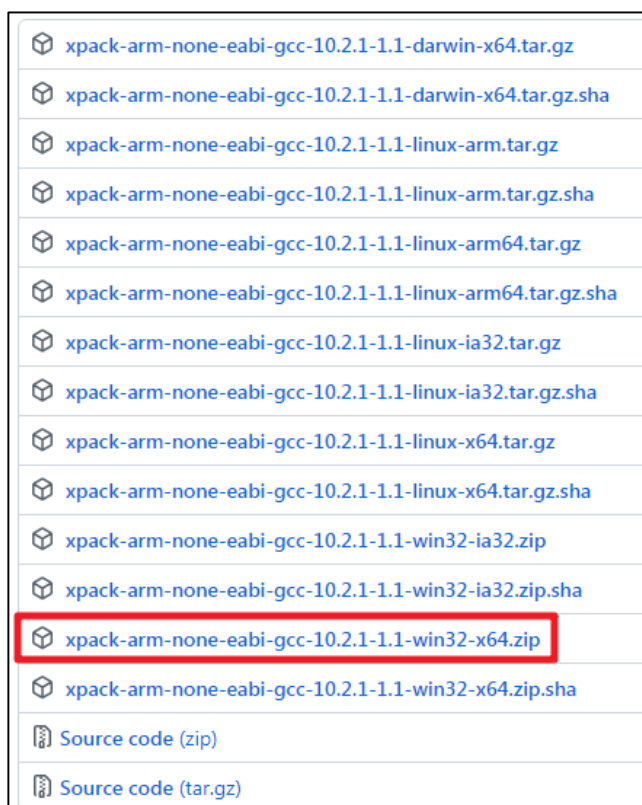
3.1.1. ARM cross toolchains installation

















- Download the `xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-x64.zip`

Visit <https://github.com/xpack-dev-tools/arm-none-eabi-gcc-xpack/releases/> to choose to download different versions of the ARM cross toolchains.

In this guide, choose to download `xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-x64.zip` and the download address is : <https://github.com/xpack-dev-tools/arm-none-eabi-gcc-xpack/tags>

Figure 3-1. Download ARM cross toolchains



 xpack-arm-none-eabi-gcc-10.2.1-1.1-darwin-x64.tar.gz
 xpack-arm-none-eabi-gcc-10.2.1-1.1-darwin-x64.tar.gz.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-arm.tar.gz
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-arm.tar.gz.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-arm64.tar.gz
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-arm64.tar.gz.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-ia32.tar.gz
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-ia32.tar.gz.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-x64.tar.gz
 xpack-arm-none-eabi-gcc-10.2.1-1.1-linux-x64.tar.gz.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-ia32.zip
 xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-ia32.zip.sha
 xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-x64.zip
 xpack-arm-none-eabi-gcc-10.2.1-1.1-win32-x64.zip.sha
 Source code (zip)
 Source code (tar.gz)

3.1.2. RISC-V cross toolchains installation

- Download the `xpack-riscv-none-embed-gcc-10.1.0-1.1-win32-x64.zip`

Visit <https://xpack.github.io/riscv-none-embed-gcc/releases/> to choose to download different versions of the RISC-V cross toolchains.

In this guide, choose to download `xpack-riscv-none-embed-gcc-10.1.0-1.1-win32-x64.zip` and the download address is : <https://github.com/xpack-dev-tools/riscv-none-embed-gcc-xpack/releases/tag/v10.1.0-1.1/>

Figure 3-2. Download RISC-V cross toolchains-1

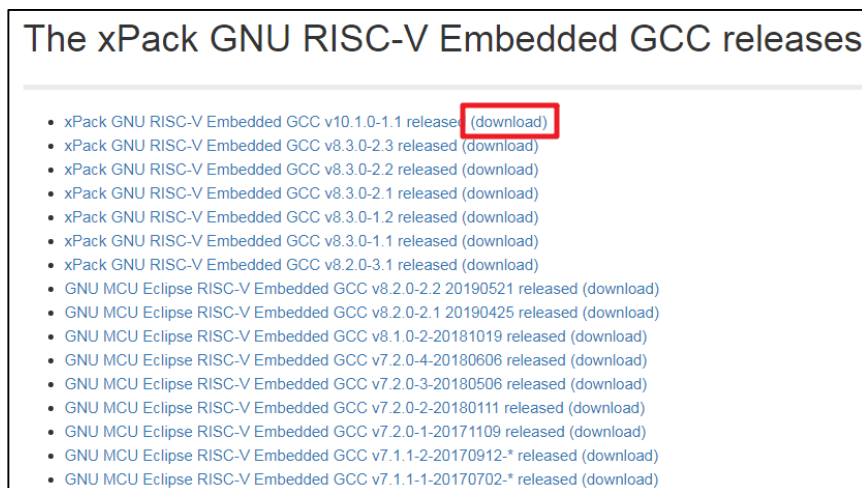
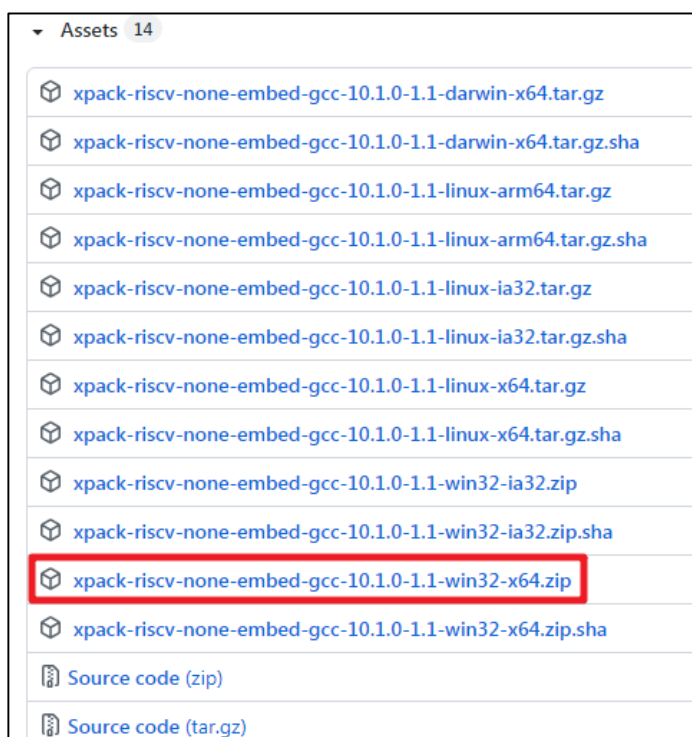


Figure 3-3. Download RISC-V cross toolchains-2



3.2. Build Tools installation

- Download the `xpack-windows-build-tools-4.2.1.2-win32-x64.zip`

Visit <https://xpack.github.io/windows-build-tools/releases/> to choose to download different versions of the Build tools.

In this guide, choose to download `xpack-windows-build-tools-4.2.1-2-win32-x64.zip` and the download address is : <https://github.com/xpack-dev-tools/windows-build-tools-xpack/releases/tag/v4.2.1-2/>

Figure 3-4. Download Build Tools-1

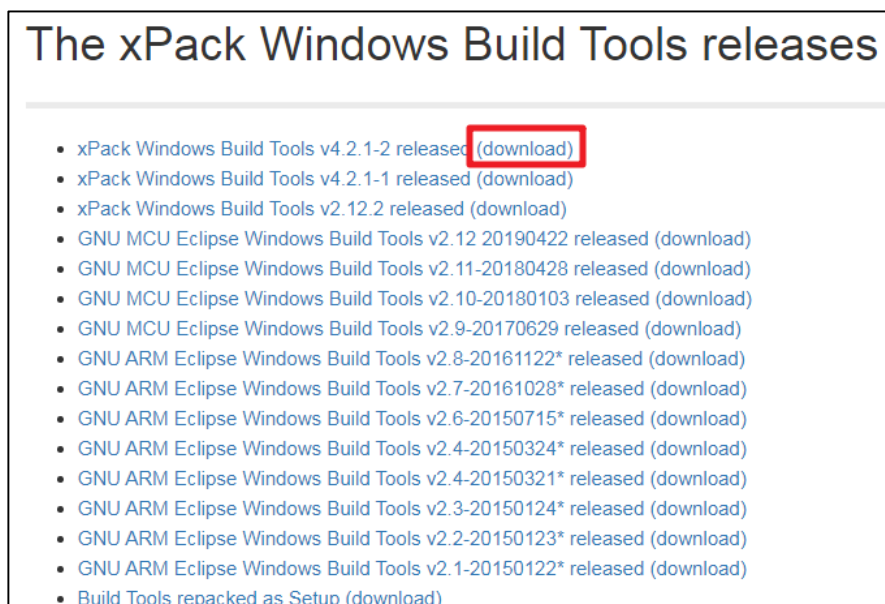
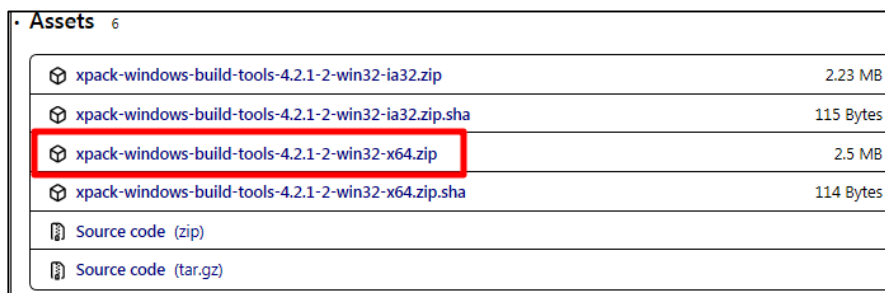


Figure 3-5. Download Build Tools-2



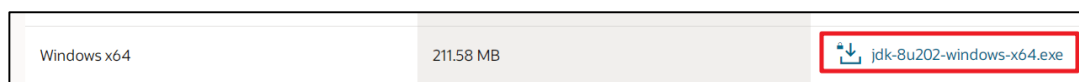
3.3. Eclipse IDE installation

3.3.1. JDK installation

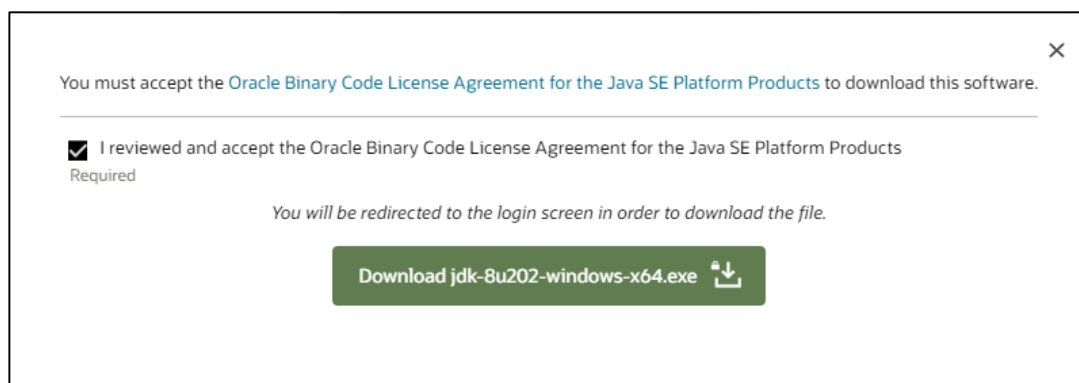
■ Download the `jdk-8u202-windows-x64.exe`

Eclipse needs to run in Java environment, so user need to install JDK before installing Eclipse. Visit <http://www.oracle.com/technetwork/java/javase/downloads/java-archive-javase8-2177648.html> to choose to download different versions of JDK tools.

In this guide, choose to download and install `jdk-8u202-windows-x64.exe`.

Figure 3-6. Download JDK-1

Before the file can be downloaded, user must accept the license agreement.

Figure 3-7. Download JDK-2

■ Install the *jdk-8u202-windows-x64.exe*

Open the CMD window and type `java -version` to test whether the JDK is installed correctly. If the JDK has been installed correctly, user can get similar output as shown in [Figure 3-8. JDK version test](#).

Figure 3-8. JDK version test

```
C:\Users\T...>java -version
java version "1.8.0_202"
Java(TM) SE Runtime Environment (build 1.8.0_202-b08)
Java HotSpot(TM) 64-Bit Server VM (build 25.202-b08, mixed mode)
```

3.3.2. Eclipse IDE for GNU ARM & RISC-V C/C++ Developers installation

■ Download the *eclipse-embedcpp-2021-03-R-win32-x86_64.zip*

Visit <https://eclipse-embed-cdt.github.io/packages/releases/> to download different versions of Eclipse IDE.

In this guide, choose to download and install *eclipse-embedcpp-2021-03-R-win32-x86_64.zip*.

The download address is:

https://www.eclipse.org/downloads/download.php?file=/technology/epp/downloads/release/2021-03/R/eclipse-embedcpp-2021-03-R-win32-x86_64.zip

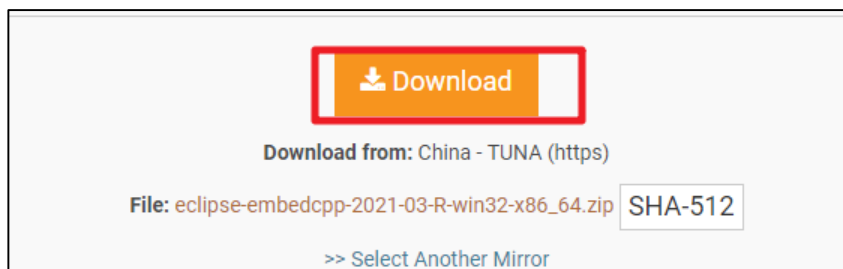
Figure 3-9. Download Eclipse-1



Figure 3-10. Download Eclipse-2



Figure 3-11. Download Eclipse-3



3.4. Debug Tools driver installation

3.4.1. OpenOCD installation

- Download the *OpenOCD.exe*

OpenOCD software does not need to be installed, just open and use. The OpenOCD software for GD32 MCU can be obtained from the original GD factory.

3.4.2. Segger J-Link installation

- Download the J-Link software

Visit <https://www.segger.com/downloads/jlink#Documentation> to download different versions of J-Link drivers.

In this guide, choose to download and install J-LinkV7.54b.

Figure 3-12. Download J-Link driver



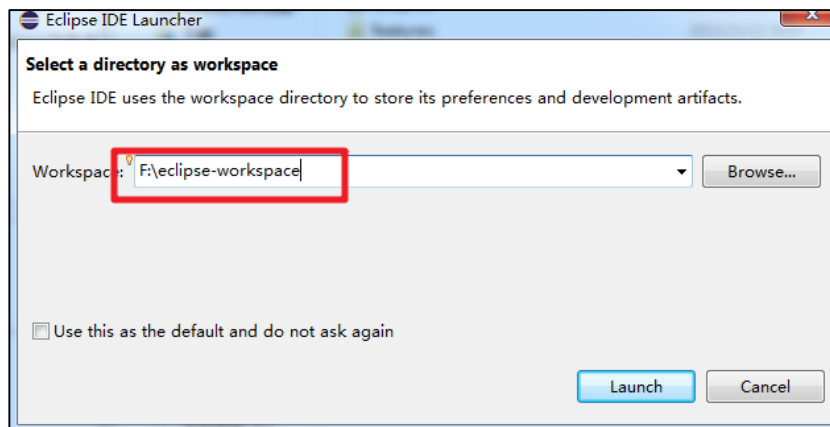
After the download is completed, just install it directly.

4. Eclipse startup and configurations

4.1. Create workspace

The Eclipse software itself is a green software and does not need to be installed. Just double-click the eclipse.exe in the eclipse folder to start Eclipse, as shown in [Figure 4-1. Eclipse IDE Launcher](#).

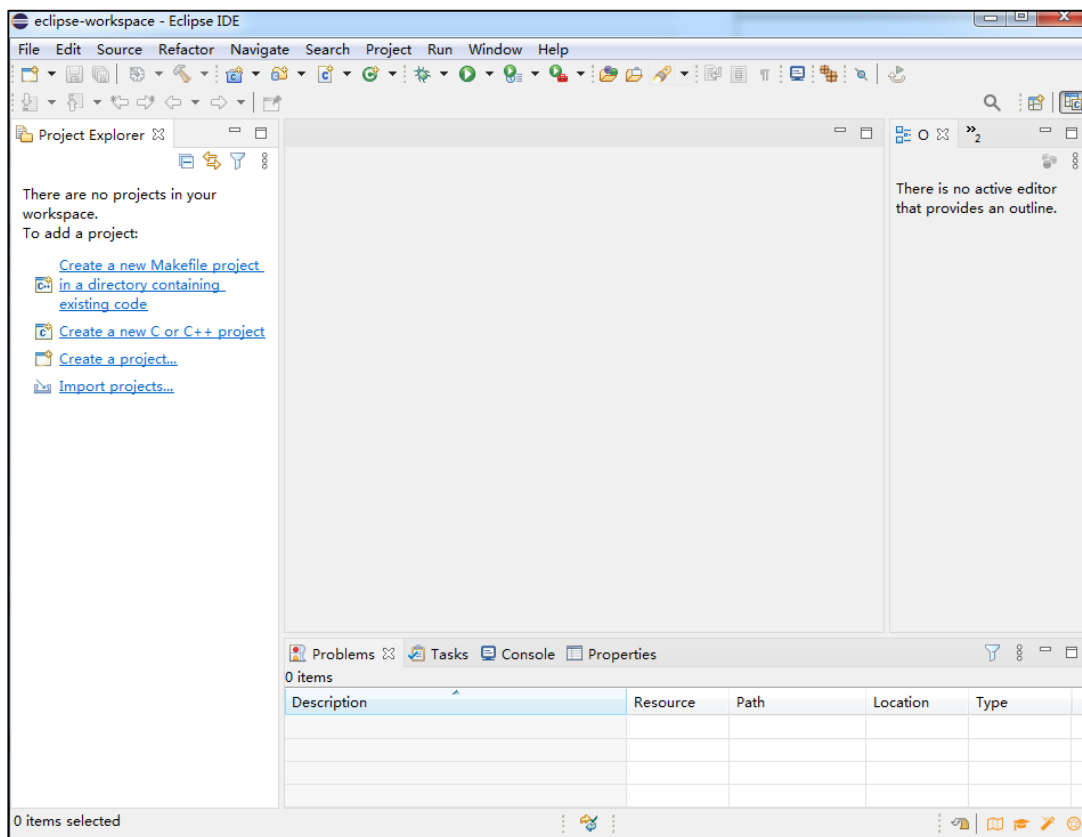
Figure 4-1. Eclipse IDE Launcher



As shown in [Figure 4-1. Eclipse IDE Launcher](#), select the local English path to create a workspace. Click Launch. (Note: the path depth can not be too deep)

After entering the welcome interface, user can choose to close the welcome in the upper left corner or open the workbench icon in the upper right corner to enter the main interface.

Figure 4-2. Eclipse workspace

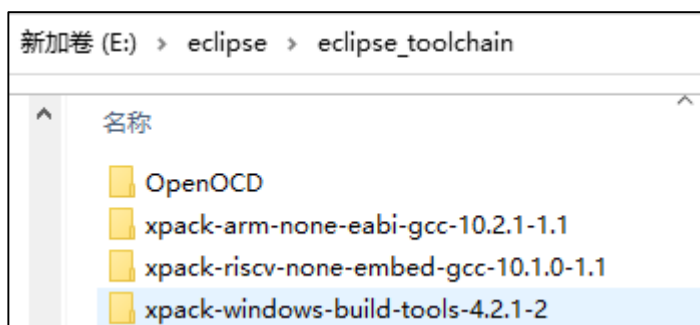


Multiple projects can be contained in the same workspace.

4.2. Set Build Tools path

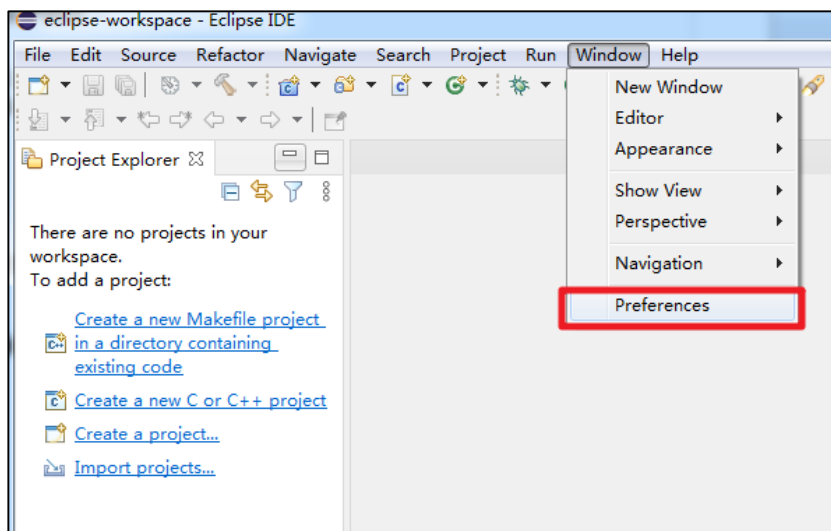
Create an `eclipse_toolchain` folder under the eclipse installation path. Decompress the ARM/RISCV cross-compilation chain, Build tool and OpenOCD downloaded in [Tool installation instructions](#) and place them in this folder.

Figure 4-3. eclipse_toolchain folder



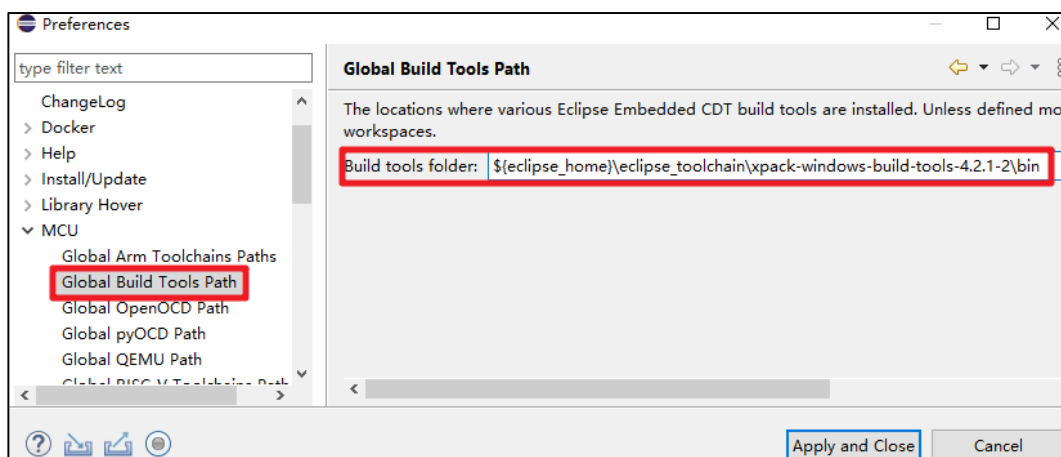
Open “Window->Preferences” option.

Figure 4-4. Eclipse Window Preferences option



Select “MCU->Global Build Tools Path” option to set the global build tool path :
`${eclipse_home}\eclipse_toolchain\xpack-windows-build-tools-4.2.1-2\bin`

Figure 4-5. Set Build Tools path

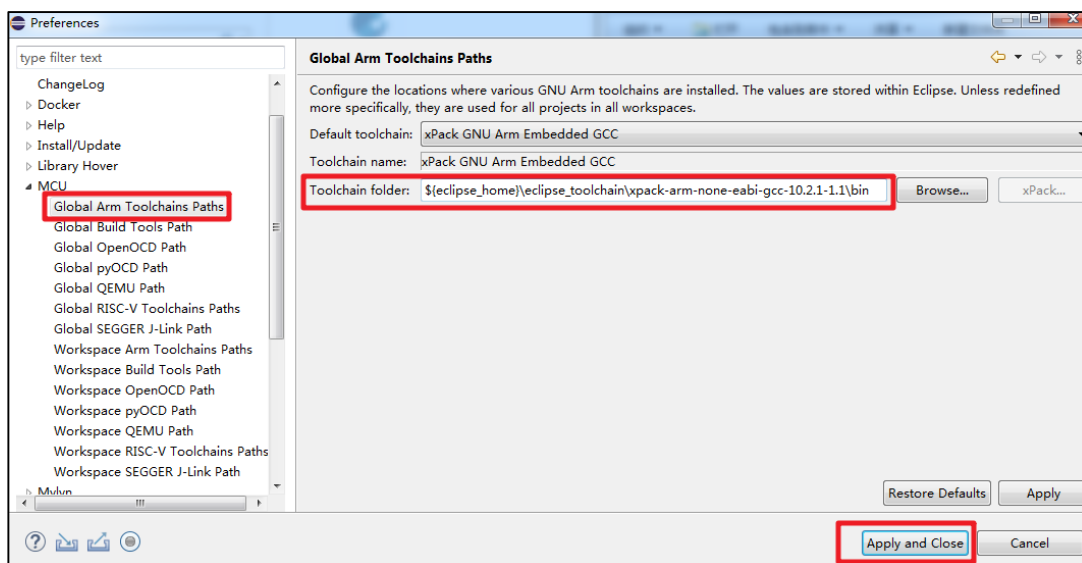


Note: The path configured here is configured as a relative path.

4.3. Set ARM Toolchains path

Select “MCU->Global Arm Toolchains Path” option to set the Arm Toolchains path :
`${eclipse_home}\eclipse_toolchain\xpack-arm-none-eabi-gcc-10.2.1-1.1\bin`

Figure 4-6. Set ARM Toolchains path

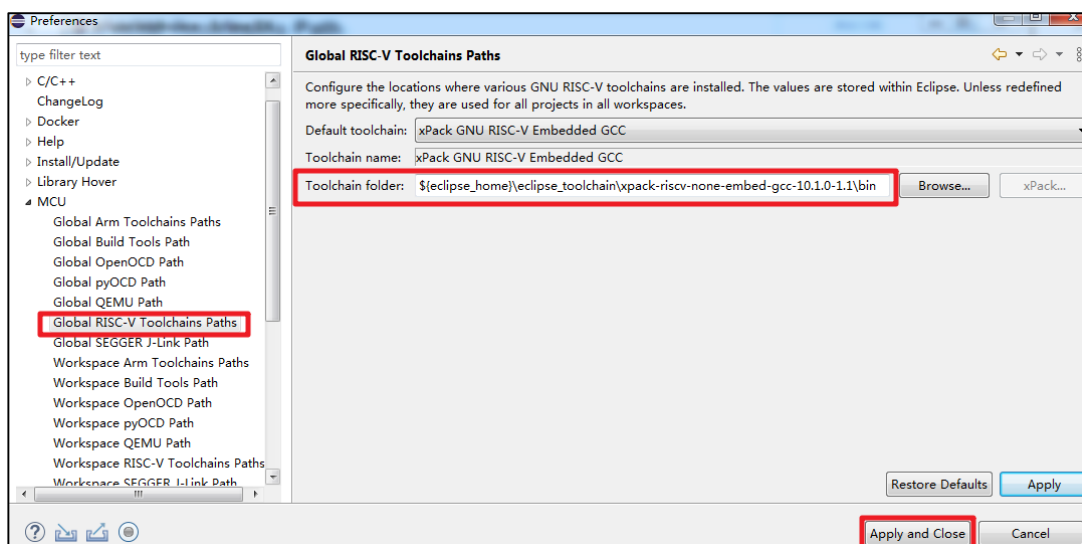


Note: The path configured here is configured as a relative path.

4.4. Set RISC-V Toolchains path

Select “MCU->Global RISC-V Toolchains Path” option to set the RISC-V Toolchains path :
`${eclipse_home}\eclipse_toolchain\xpack-riscv-none-embed-gcc-10.1.0-1.1\bin`

Figure 4-7. Set RISC-V Toolchains path

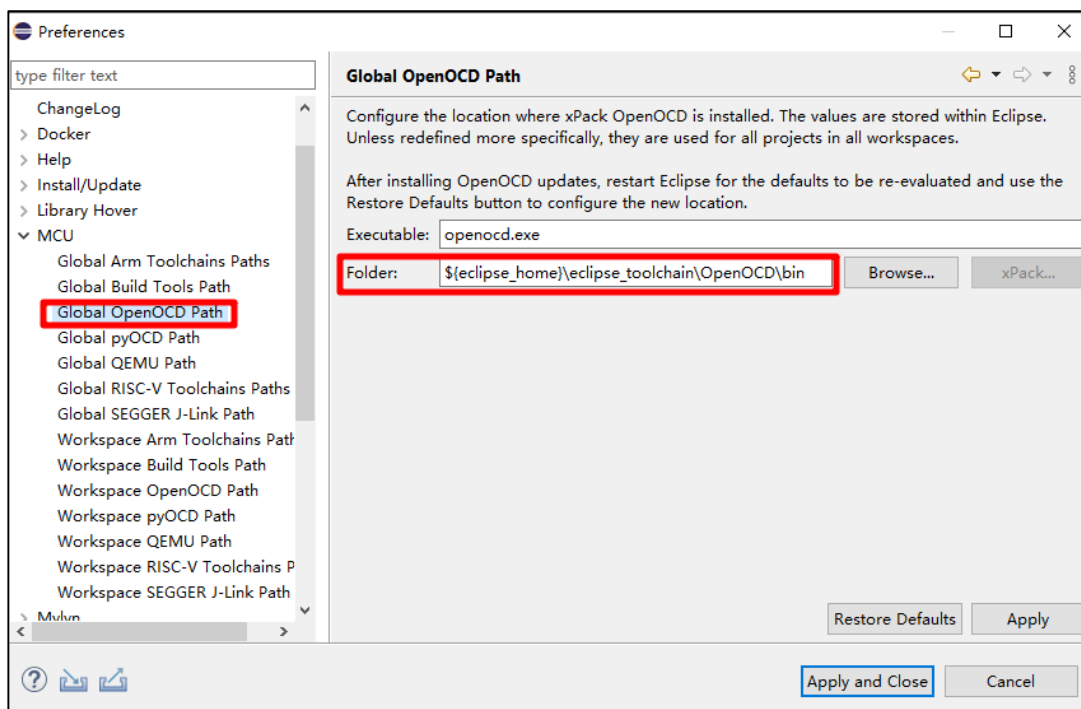


Note: The path configured here is configured as a relative path.

4.5. Set OpenOCD path

Select “MCU->Global OpenOCD Path” option to set the OpenOCD path :
\${eclipse_home}\eclipse_toolchain\OpenOCD\bin

Figure 4-8. Set OpenOCD path

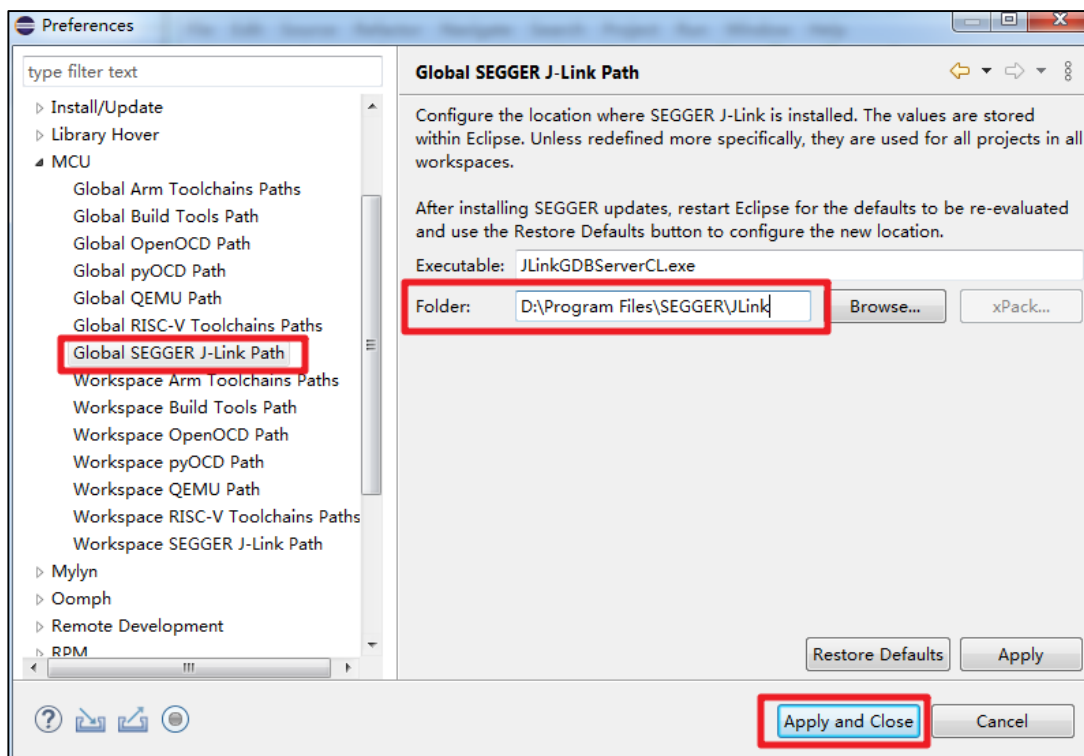


Note: The path configured here is configured as a relative path.

4.6. Set SEGGER J-Link path

Select “MCU->Global SEGGER J-Link Path” option to set the SEGGER J-Link path. Here select the local absolute path, in this paper the path is D:\Program Files\SEGGER\JLink.

Figure 4-9. Set SEGGER J-Link Path



At this point, all the configurations of Eclipse IDE have been completed, and user can use the configured Eclipse to develop GD32 ARM/RISC-V projects.

5. Revision history

Table 5-1. Revision history

Revision No.	Description	Date
1.0	Initial Release	May.30 2022

Important Notice

This document is the property of GigaDevice Semiconductor Inc. and its subsidiaries (the "Company"). This document, including any product of the Company described in this document (the "Product"), is owned by the Company under the intellectual property laws and treaties of the People's Republic of China and other jurisdictions worldwide. The Company reserves all rights under such laws and treaties and does not grant any license under its patents, copyrights, trademarks, or other intellectual property rights. The names and brands of third party referred thereto (if any) are the property of their respective owner and referred to for identification purposes only.

The Company makes no warranty of any kind, express or implied, with regard to this document or any Product, including, but not limited to, the implied warranties of merchantability and fitness for a particular purpose. The Company does not assume any liability arising out of the application or use of any Product described in this document. Any information provided in this document is provided only for reference purposes. It is the responsibility of the user of this document to properly design, program, and test the functionality and safety of any application made of this information and any resulting product. Except for customized products which has been expressly identified in the applicable agreement, the Products are designed, developed, and/or manufactured for ordinary business, industrial, personal, and/or household applications only. The Products are not designed, intended, or authorized for use as components in systems designed or intended for the operation of weapons, weapons systems, nuclear installations, atomic energy control instruments, combustion control instruments, airplane or spaceship instruments, transportation instruments, traffic signal instruments, life-support devices or systems, other medical devices or systems (including resuscitation equipment and surgical implants), pollution control or hazardous substances management, or other uses where the failure of the device or Product could cause personal injury, death, property or environmental damage ("Unintended Uses"). Customers shall take any and all actions to ensure using and selling the Products in accordance with the applicable laws and regulations. The Company is not liable, in whole or in part, and customers shall and hereby do release the Company as well as its suppliers and/or distributors from any claim, damage, or other liability arising from or related to all Unintended Uses of the Products. Customers shall indemnify and hold the Company as well as its suppliers and/or distributors harmless from and against all claims, costs, damages, and other liabilities, including claims for personal injury or death, arising from or related to any Unintended Uses of the Products.

Information in this document is provided solely in connection with the Products. The Company reserves the right to make changes, corrections, modifications or improvements to this document and Products and services described herein at any time, without notice.